

Bayesian group bridge composite quantile regression

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Abstract

Bayesian regularized composite quantile regression (CQR) method with group bridge penalty is adopted to conduct covariate selection and estimation in CQR. MCMC algorithm was improved for posterior inference employing a scale mixture of normal of the asymmetric Laplace distribution (ALD). The suggested algorithm uses priors for the coefficients of regression, which are scale mixtures of multivariate uniform distributions with a particular Gamma distribution as a mixing distribution. Simulation results and analyses of real data show that the suggested MCMC sampler has excellent mixing feature and outperforms the current approaches in terms of prediction accuracy and model selection.

Keywords: Bayesian inference, Composite quantile regression, Group bridge, MCMC, scale mixture of uniform.

1. Introduction

The normal linear regression model supposes that an outcomes vector $y = (y_1, \dots, y_n)'$ can be written as

$$y = b_0 \mathbf{1} + X\beta + \varepsilon, \quad (1)$$

where $X = (x_1, \dots, x_n)'$ is a $n \times p$ covariates matrix, b_0 is the intercept, $\mathbf{1}$ is an $n \times 1$ unit vector, $\beta = (\beta_1, \dots, \beta_p)'$, $\varepsilon = (\varepsilon_1, \dots, \varepsilon_n)'$ are independent, as well as ε_i has a Gaussian distribution having mean 0 and variance σ^2 . According to model (1), it's supposed that only an unfamiliar subset from covariates are effective in the regression; therefore, the issue of covariate selecting is to find this unfamiliar subset of covariates.

Traditional approaches to model selection based on the observed data log likelihood, comparing a set of candidate models include Mallows's C_p (Mallows, 1973), Akaike information criterion (AIC; Akaike, 1973), and Bayesian information criterion (BIC; Schwarz et al., 1978). Among the new approaches that are based on regularization and selection operator involve the bridge regression (Frank and Friedman,

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1993), lasso (Tibshirani, 1996), smoothly clipped absolute deviation (Fan and Li, 2001), fused lasso (Tibshirani et al., 2005), adaptive lasso (Zou, 2006), graphical lasso (Yuan and Lin, 2006), dantzig selector (Candes and Tao, 2007), and matrix completion (Candès and Tao, 2010; Mazumder et al., 2011), among others. These approaches are setup for selecting individual covariates. However, covariates are naturally grouped in many real studies. An important example appears in association studies, genes may form overlapping sets where each gene can be involved in multiple tracks (Jacob et al., 2009). For this and other situations, Yuan and Lin (2006) suggested the group lasso penalty for choosing covariates groups by introducing a suitable expansion of the lasso penalty. Since Yuan and Lin (2006), over the years, various group lasso methods have been improved for dealing with chosen groups of covariates (see for example, Breheny, 2015; Huang et al., 2012, 2009; Meier et al., 2008; Park and Yoon, 2011; Qian et al., 2016; Simon et al., 2013; Simon and Tibshirani, 2012).

Although covariate selection methods in standard mean regression models have been well developed, we frequently require to assess effects of covariates on outcome variable at various quantile levels. Koenker and Bassett (1978) suggested quantile regression (QR) to overcome this issue. Compared to standard mean regression, QR is more strong to data outliers than standard mean regression, and can provide a more clear picture of the relation between covariates and outcome of interest. However, for linear regression models, Zou and Yuan (2008) indicated that QR may result in an arbitrarily tiny relative efficiency when compared with the standard mean regression. Since, QR at one quantile can provide more efficient estimators than QR at another quantile, Zou and Yuan (2008) suggested a composite QR (CQR) approach to simultaneously study multiple QR models. They proved that, irrespective of the error distribution, the relative efficiency of the CQR estimator is higher than 70% when compared to the mean regression estimator. Recently, when p is finite, CQR has been employed in covariate selection methods; for example see, Zou and Yuan (2008), Bradic et al. (2011) and Jiang et al. (2012). In this paper, we suggest a Bayesian framework to combine CQR and group bridge penalty together to perform model selection and estimation of coefficients simultaneously.

We introduce the CQR with the group bridge penalty in Section 2. We also outline the Bayesian sampler algorithm for CQR. Section 3 is where we run examples of simulation to investigate the performance of the suggested approach, and we explain our approach employing the prostate cancer data in Section 4. Finally, in Section 5, we conclude with a summarized discussion.

2. Methods

2.1 QR

QR (Koenker and Bassett, 1978) has acquired growing popularity since it makes few assumptions about the error distribution. For the θ th quantile ($0 < \theta < 1$), the linear QR model is $y = b_\theta + X\beta + \epsilon$, where $\epsilon = (\epsilon_1, \dots, \epsilon_n)$ 'are independent, and their θ th quantiles equal to zero. The θ th QR model takes the form of

$$Q_{y_i}(x_i) = b_\theta + x_i'\beta, \quad (2)$$

where b_θ is the quantile intercept. The regression parameters b_θ and β are estimated by minimizing (Koenker and Bassett, 1978):

$$b_\theta, \beta \min \sum_{i=1}^n \rho_\theta(y_i - b_\theta - x_i'\beta), \quad (3)$$

where $\rho_\theta(w) = w\theta - wI(w \leq 0)$ denotes the quantile check (loss) function and $I(\cdot)$ denotes the indicator function. The ALD provides a possible parametric correlation between the minimization issue in (3) and the maximum likelihood theorem (Koenker and Machado, 1999; Yu and Moyeed, 2001). The ALD density function for the response y is

$$f(\mu, \sigma) = \frac{\theta(1-\theta)}{\sigma} \exp\left\{-\frac{\rho_\theta(y-\mu)}{\sigma}\right\}, \quad (4)$$

where σ is the scale parameter and μ is the location parameter. Yu and Moyeed (2001) introduced a Bayesian framework for QR employing the ALD for the errors, and the MCMC Metropolis-Hastings sampling algorithm is utilized to (approximately) draw β from its conditional distribution. Kozumi and Kobayashi (2011) improved an efficient Gibbs sampling algorithm for Bayesian QR by assuming that the random variable $\epsilon_i = (1-2\theta)w_i + \nu(2\sigma w_i z_i)$ follows the ALD, where w_i and z_i have an exponential distribution having scale parameter $(\theta(1-\theta)/\sigma)$ and a standard normal distribution, respectively (see, Alhamzawi and Yu, 2012; Alshaybawee et al., 2017; Alhamzawi and Ali, 2018; Alhamzawi et al., 2019; Alhamzawi, Taha Mohammad Ali, 2020). As the conditional distribution of y_i given w_i is normal having mean $b_\theta + x_i'\beta + (1-2\theta)w_i$ and variance $2\sigma w_i$, the density of y_i is given by

$$= \frac{1}{\sqrt{4\pi\sigma w_i}} \exp\left\{-\frac{p(y_i|x_i, \beta, b_\theta, w_i, \sigma) + (y_i - b_\theta - x_i'\beta - (1-2\theta)w_i)^2}{4\sigma w_i}\right\} \quad (5)$$

2.2 CQR

CQR (Zou and Yuan, 2008) has acquired growing popularity as it can combine information of numerous quantiles simultaneously to get a group of good estimations. Denote $0 < \theta_1 < \theta_2 < \dots < \theta_K < 1$, where($\theta_1 < \theta_2 < \dots < \theta_K < 1$)

$\theta_k = k \setminus (K+1)$. The CQR estimators of $b\theta = (b\theta_1, \dots, b\theta_K)$ and β can be estimated by minimizing

$$(\hat{b}_\theta, \hat{\beta}) = b_\theta, \beta \min \sum_{i=1}^n \{ \sum_{k=1}^K \rho_{\theta_k}(y_i - b_{\theta_k} - x_i' \beta) \}, \quad (6)$$

Huang and Chen (2015) and Alhamzawi (2016) proposed Bayesian formulations for CQR using the ALD for the errors. Under these formulations, the joint distribution of y is

$$p(X, \beta, b_\theta, w, \sigma) = \prod_{k=1}^K \prod_{i=1}^n \left(\frac{1}{\sqrt{4\pi\sigma w_{ik}}} \right) \exp \left\{ -\frac{(y_i - b_{\theta_k} - x_i' \beta - \xi_k w_{ik})^2}{4\sigma w_{ik}} \right\}, \quad (7)$$

where $w = (w_{11}, \dots, w_{1K}), w_k = (w_{1k}, \dots, w_{nk})$ and $\xi_k = 1 - 2\theta_k$.

2.3 CQR with the group bridge penalty

Assume that the covariates are collected into G groups so that $x_i = (x_{i1}, \dots, x_{iG})'$, $\beta = (\beta_1, \dots, \beta_G)'$ is the m_g -dimensional coefficient vector of the g th group covariates x_{ig} , $\sum_{g=1}^G m_g = p$ and $G < p$. In this paper, we define the following group bridge regularized CQR:

$$(\hat{b}_\theta, \hat{\beta}) = b_\theta, \beta \min \sum_{i=1}^n \{ \sum_{k=1}^K \rho_{\theta_k}(y_i - b_{\theta_k} - x_i' \beta) \} + \sum_{g=1}^G \lambda_g \|\beta_g\|_1^\alpha, \quad (8)$$

Where $\|\beta_g\|_1$ is the L1 norm of β_g , $\lambda_g > 0$, $g = 1, \dots, G$ are the group-specific shrinkage parameters and $\alpha > 0$ denotes the concavity parameter. The bridge parameter α does covariate selection when $\alpha \in (0, 1]$, and shrinks the coefficients of regression when $\alpha > 1$. From a Bayesian point of view, one may define the following group bridge prior on the coefficients (Gómez-Sánchez-Manzano et al., 2008; Gómez-Villegas et al., 2011; Mallick and Yi, 2018):

$$p(\alpha, \lambda_1, \dots, \lambda_G) \propto \prod_{g=1}^G \exp(-\lambda_g \|\beta_g\|_1^\alpha). \quad (9)$$

If we remove the dependence on the group index g , the prior for a group bridge may be written as follows

$$p(\beta) = \frac{\lambda^\frac{p}{\alpha} \Gamma(\frac{p+1}{\alpha})}{2^p \Gamma(\frac{p}{\alpha})} \exp(-\lambda \|\beta\|_1^\alpha). \quad (10)$$

If we put the group bridge prior (9) on β and assume the errors ϵ_i is from the ALD (4), the conditional distribution of β is

$$\propto \exp \left\{ - \sum_{i=1}^n \sum_{k=1}^K \frac{(y_i - b_{\theta_k} - x_i' \beta - \xi_k w_{ik})^2}{4\sigma w_{ik}} - \sum_{g=1}^G \lambda_g \|\beta_g\|_1^\alpha \right\}. \quad (11)$$

So minimizing the group bridge regularized CQR (8) is equivalent to maximizing the composite likelihood (11). Mallick and Yi (2018) show that the group bridge prior may be expressed as a scale mixture of multivariate uniform (SMU) distribution, the mixing density is a specific Gamma distribution, in other words, $\beta|u \sim$ Multivariate Uniform (A), where $A = \{\beta \in R^q : \|\beta_g\|_1^\alpha < u\}$, $u > 0$ and $u \sim$ Gamma ($q/\alpha + 1, \lambda$). Putting Beta prior on α and Gamma priors on λ_g and σ_k , the Bayesian hierarchical model for CQR with group bridge penalty (8) is as follows

$$\begin{aligned} y_i &= \prod_{k=1}^K (b_{\theta_k} + x_i' \beta + \xi_k w_{ik} + \sqrt{2\sigma w_{ik}} z_i), i = 1, \dots, n, \\ w|\sigma &\sim \prod_{k=1}^K \prod_{i=1}^n \frac{\theta_k(1 - \theta_k)}{\sigma} \exp\left(-\frac{\theta_k(1 - \theta_k)}{\sigma} w_{ik}\right), \\ z &\sim \prod_{i=1}^n N(0,1), \\ \beta_g|u_{g,\alpha} &\sim \text{Multivariate Uniform}(\Omega_g) \text{ independently for } g \\ &= 1, \dots, G, \\ \text{where } \Omega_g &= \{\beta_g \in R^{m_g} : \|\beta_g\|_1^\alpha < u_g\}, \\ u_1, \dots, u_G|\lambda_1, \dots, \lambda_G, \alpha &\sim \prod_{g=1}^G \text{Gamma}\left(\frac{m_g}{\alpha} + 1, \lambda_g\right), \\ \lambda_1, \dots, \lambda_G &\sim \prod_{g=1}^G \text{Gamma}(a, b), \end{aligned} \quad (12)$$

$$\alpha \sim \text{Beta}(c, d),$$

$$\sigma \sim \text{Gamma}(r, \delta),$$

where $\mathbf{u} = (u_1, \dots, u_G)$, and $\boldsymbol{\lambda} = (\lambda_1, \dots, \lambda_G)$. It's clear that the full conditional posteriors may be obtained by employing easy algebra for the prior description and the parameters of interest ($\mathbf{b}_\theta, \boldsymbol{\beta}, \sigma, \mathbf{w}, \mathbf{u}, \boldsymbol{\lambda}, \alpha$) can be sampled as listed in Figure 1.

Figure 1: MCMC sampling for the Bayesian group bridge CQR.

Input: (\mathbf{y}, \mathbf{X})
Initialize: $(b_\theta, \boldsymbol{\beta}, \sigma, \mathbf{w}, \mathbf{u}, \boldsymbol{\lambda}, \alpha)$
for $t = 1, \dots, (t_{\max} + t_{\text{burn-in}})$ **do**

1. Sample $\boldsymbol{\beta} | \cdot \sim N_p(\boldsymbol{\beta}, B) \prod_{g=1}^G I\{\|\boldsymbol{\beta}_g\|_2^\alpha < u_g\}$, where $B^{-1} = (\sum_{i=1}^n \sum_{k=1}^K \frac{x_i x_i'}{2\sigma w_{ik}})$ and
$$\boldsymbol{\beta} = B \left(\sum_{i=1}^n \sum_{k=1}^K \frac{x_i (y_i - b_{\theta_k} - \mathbf{x}_i' \boldsymbol{\beta} - \xi_k w_{ik})}{2\sigma w_{ik}} \right)$$
2. Sample $b_{\theta_k} | \cdot \sim N \left(\frac{\sum_{i=1}^n (y_i - b_{\theta_k} - \mathbf{x}_i' \boldsymbol{\beta} - \xi_k w_{ik}) / 2\sigma w_{ik}}{\sum_{i=1}^n 1 / 2\sigma w_{ik}}, \frac{1}{\sum_{i=1}^n 1 / 2\sigma w_{ik}} \right)$
3. Sample $w_{ik} | \cdot \sim \text{inverse Gaussian} \left(\frac{1}{2\sigma}, \sqrt{\frac{1}{(y_i - b_{\theta_k} - \mathbf{x}_i' \boldsymbol{\beta})^2}} \right)$
4. Sample $\sigma | \cdot \sim \text{inverse Gamma} \left(\frac{3nK}{2} + r, \frac{1}{2} \sum_{i=1}^n \sum_{k=1}^K \frac{(y_i - b_{\theta_k} - \mathbf{x}_i' \boldsymbol{\beta} - \xi_k w_{ik})^2}{2w_{ik}} + \sum_{i=1}^n \sum_{k=1}^K \theta_k (1 - \theta_k) w_{ik} + \delta \right)$
5. Sample $\mathbf{u} | \cdot \sim \prod_{g=1}^G \text{Exponential}(\lambda_g) I\{u_g > \|\boldsymbol{\beta}_g\|_1^\alpha\}$
6. Sample $\boldsymbol{\lambda} | \cdot \sim \prod_{g=1}^G \text{Gamma} \left(a + m_g / \alpha, b + \sum_{g=1}^G \|\boldsymbol{\beta}_g\|_1^\alpha \right)$
7. Sample $\alpha | \cdot \sim \alpha^{c-1} (1 - \alpha)^{d-1} \prod_{g=1}^G \frac{\lambda_g^{m_g/\alpha}}{\Gamma(\frac{m_g}{\alpha} + 1)} \exp(-\lambda_g \|\boldsymbol{\beta}_g\|_1^\alpha)$, which has no closed form.

Since $p(\cdot)$ is a log-concave, we update α using Adaptive

3. Simulation Studies

Here, we use simulations of Monte Carlo to illustrate the performance of Bayesian group Bridge CQR (BgBCQR) with comparison to the lasso CQR (LCQR, Zou and Yuan, 2008), Bayesian lasso CQR (BLCQR, Huang and Chen, 2015), Bayesian group bridge regression (BgBR, Mallick and

Yi, 2018), group bridge regression (gBR, Huang et al., 2009) and group Lasso regression (gLR, Yuan and Lin, 2005). The Bayesian estimations are posterior means employing 11,000 draws of the MCMC algorithm following burn-in the first 2,000 draws. For our approach, we set $a = 1$, $b = 0.1$, $r = 10$, $\delta = 10$, $c = 0.1$, and $d = 0.1$.

We generate data using the following real model

$$y = X\boldsymbol{\beta} + \varepsilon$$

In each generated data, we consider three different choices for the error distribution: $N(0,9)$, $t(3)$ distribution having (3) freedom degrees, and $\chi_{(3)}^2$ distribution having (3) freedom degrees. Additionally, we run 100 replications. In each replication, we simulate a training set of 20 observations and a testing set of 200 observations. Example 1 (Li et al., 2010). In this example, the rows of the design matrix X are provided by $(I(S_1 = 0), I(S_1 = 1), I(S_1 = 2), \dots, I(S_5 = 0), I(S_5 = 1), I(S_5 = 2))$, where the latent variables $S = (S_1, \dots, S_5)'$ are simulated independently from $N(0, \boldsymbol{\Sigma})$ with the (i, j) th element of $\boldsymbol{\Sigma}$ is $\rho^{|i-j|}$ and $\rho = 0.5$. Each latent variable S_j for $j = 1, \dots, 5$ is trichotomized as zero, one or two, depending on whether it's less than $F^{-1}(1/3)$, between $F^{-1}(1/3)$ and $F^{-1}(2/3)$, or greater than $F^{-1}(2/3)$, where F^{-1} is the quantile function to standard normal distribution. We set the regression coefficients vector as $\boldsymbol{\beta} = ((-1.2, 1.8, 0), (0, 0, 0), (0.5, 1, 0), (0, 0, 0), (1, 1, 0))$. Thus, the regression parameters in a group may be either all zero, all nonzero or partly. We use $\{n_T, n_P\} = \{20, 400\}$, $\{50, 400\}$ and $\{100, 400\}$ respectively, to simulate datasets, where n_T stands for the number of the observations in the training set, while n_P stands for the number of the observations in the testing set. The experimental outcomes are presented in Table 1. Here, in terms of prediction accuracy, our suggested approach outperforms current Bayesian and non-Bayesian approaches.

Example 2 (High Correlation Example). The setup for this example is identical to the first, excepting we set $\rho = 0.95$. The experimental outcomes are presented in Table 2. Here also, in terms of prediction accuracy, our suggested approach outperforms the other methods.

Example 3. The setup for this example is identical to the first, excepting we set the coefficients of regression vector as $\boldsymbol{\beta} = ((0.5, 1, 1.5, 2, 2.5), (2, 2, 2, 2, 2), (0, 0, 0, 0, 0))$. Thus, in each group, the regression parameters are either all nonzero or all zero. The experimental outcomes are shown in Table 3. Again, we may observe that in terms of prediction accuracy, our proposed approach outperforms the other approaches.

Overall, the simulations show that all of the Bayesian approaches have the same accuracy of the prediction in most of the cases, so often outperform their frequentist counterparts in terms of prediction accuracy all over a wide range of scenarios.

Table 1: Median of mean absolute deviations (MMAD) with the standard deviations of MAD (SD) for Example 1. The bold numbers of MMAD stands for the least MMAD in each category.

Method	$n\tau$	Error					
		$N(0, 9)$		$t^{(3)}$		$\chi^2_{(3)}$	
		MMAD	SD	MMAD	SD	MMAD	SD
<u>gLR</u>	20	1.4278	1.4021	1.4325	1.4690	1.7025	1.6536
<u>gBR</u>	20	1.4166	1.4722	1.6533	1.8253	1.9837	2.3613
<u>BgBR</u>	20	1.3728	1.2083	1.5241	1.3422	1.6572	1.5344
<u>BgBCQR</u>	20	1.3213	1.4082	1.5221	1.3314	1.5267	1.4362
<u>gLR</u>	50	1.4099	1.5504	1.3722	1.4797	1.4359	1.4685
<u>gBR</u>	50	1.5313	2.1991	1.4850	2.0498	1.5083	2.0028
<u>BgBR</u>	50	1.3121	1.4467	1.2901	1.3788	1.3283	1.3936
<u>BgBCQR</u>	50	1.2614	1.1231	1.1751	1.1238	1.3781	1.5865
<u>gLR</u>	100	1.2543	1.4199	1.2347	1.3747	1.2459	1.3555
<u>gBR</u>	100	1.3013	1.9240	1.2365	1.8437	1.2331	1.7848
<u>BgBR</u>	100	1.1841	1.3446	1.1328	1.3026	1.1281	1.2801
<u>BgBCQR</u>	100	1.0021	1.5278	1.1206	1.4711	1.1061	1.4311
<u>gLR</u>	200	1.1197	1.3299	1.0750	1.2976	1.0859	1.2699
<u>gBR</u>	200	1.0892	1.7387	1.0194	1.6856	1.0292	1.6394
<u>BgBR</u>	200	1.0148	1.2540	0.9735	1.2209	0.9844	1.1984
<u>BgBCQR</u>	200	0.9893	1.3966	0.9059	1.3601	0.9137	1.3264

Table 2: MMAD with the standard deviations of MAD (SD) for Example 2. The bold numbers of MMAD stands for the least MMAD in each category.

Method	$n\tau$	Error					
		$N(0, 9)$		$t^{(3)}$		$\chi^2_{(3)}$	
		MMAD	SD	MMAD	SD	MMAD	SD
<u>gLR</u>	20	1.2157	1.0958	1.4045	1.5105	1.6392	3.4381
<u>gBR</u>	20	1.1169	1.6627	1.3276	2.2563	1.5980	3.8811
<u>BgBR</u>	20	1.2516	1.0141	1.3050	1.2258	1.4053	1.4456
<u>BgBCQR</u>	20	1.1087	1.3581	1.2732	1.7005	1.4008	2.1010
<u>gLR</u>	50	1.3368	3.0464	1.3128	2.8754	1.3578	2.6771
<u>gBR</u>	50	1.2352	3.4627	1.1757	3.2631	1.2064	3.0724
<u>BgBR</u>	50	1.1389	1.3623	1.1205	1.4771	1.1517	1.4497
<u>BgBCQR</u>	50	1.1123	1.9312	1.0463	1.9399	1.0749	1.8490
<u>gLR</u>	100	1.2226	2.5129	1.1945	2.3731	1.2195	2.2664
<u>gBR</u>	100	1.0464	2.8894	1.0008	2.7298	1.0234	2.6102
<u>BgBR</u>	100	1.0228	1.3897	0.9612	1.3315	0.9882	1.3033
<u>BgBCQR</u>	100	0.9636	1.7549	0.8931	1.6710	0.9162	1.6120
<u>gLR</u>	200	1.1040	2.1808	1.0616	2.0965	1.0670	2.0238
<u>gBR</u>	200	0.8993	2.5071	0.8571	2.4100	0.8449	2.3241
<u>BgBR</u>	200	0.8784	1.2708	0.8372	1.2350	0.8332	1.2030
<u>BgBCQR</u>	200	0.8304	1.5592	0.7751	1.5073	0.7689	1.4594

4. Real Data Analyses

In this section, we implement the suggested approach for the standard datasets, namely the data of prostate cancer (Stamey et al., 1989). This dataset has been utilized for illustration in previous regularization papers. In this dataset, the logarithm of prostate-specified antigen is the outcome of interest. Here is a list describing briefly the response variable and 8 covariates.

We compare the mean squared prediction errors (MMSE) for Prostate data analyses in Table 4, which shows that our suggested approach outperforms both the existing Bayesian and non-Bayesian approaches in terms of prediction accuracy.

lcavol	Log(volume of cancer)
lweight	Log(weight of the prostate)
age	Age
lbph	Log(The quantity of benign prostatic hyperplasia)
svi	Invasion of seminal vesicles
lcp	Log(capsular breakthrough)
gleason	The Gleason result
pgg45	The rate of Gleason results is four or five
lpsa	Log(prostatic specified antigen)

Table 3: MMAD with the standard deviations of MAD (SD) for Example 3. The bold numbers of MMAD stands for the least MMAD in each category.

Method	n_T	Error					
		$N(0, 9)$		$t_{(3)}$		$\chi^2_{(3)}$	
		MMAD	SD	MMAD	SD	MMAD	SD
gLR	20	0.9023	1.3315	0.9852	1.1570	0.9991	1.9758
gBR	20	1.2054	2.0352	1.3890	1.9173	1.5677	3.5526
BgBR	20	0.8993	0.9335	1.0620	0.9569	1.1418	1.4970
BgBCQR	20	1.0882	1.4828	1.1909	1.4525	1.3595	1.8149
gLR	50	0.8698	1.7703	0.8549	1.6444	0.8512	1.5493
gBR	50	1.2195	3.1602	1.1014	2.8997	1.1144	2.7275
BgBR	50	0.9995	1.3676	0.9356	1.2845	0.9457	1.2530
BgBCQR	50	1.1121	1.6576	1.0524	1.5576	1.0498	1.4973
gLR	100	0.8051	1.4692	0.7990	1.4078	0.8051	1.3559
gBR	100	0.9750	2.5649	0.9377	2.4384	0.9430	2.3289
BgBR	100	0.8438	1.1981	0.7990	1.1597	0.8272	1.1301
BgBCQR	100	0.8306	1.4276	0.7750	1.3702	0.8164	1.3255
gLR	200	0.7708	1.3108	0.7582	1.2707	0.7685	1.2389
gBR	200	0.8369	2.2343	0.7950	2.1482	0.7827	2.0760
BgBR	200	0.7502	1.0969	0.7218	1.0677	0.7216	1.0481
BgBCQR	200	0.7493	1.2841	0.7159	1.2453	0.7111	1.2131

Table 4: MMSE for Prostate data analyses.

Method	MMSE
gLR	0.48
gBR	0.48
BgBR	0.47
BgBCQR	0.45

5. Discussion

We have introduced a Bayesian analysis of group bridge CQR and employing a scale mixture of normals of the ALD, we have proposed Gibbs sampler algorithm for posterior inference. The suggested algorithm uses priors for the coefficients of regression, which are scale mixtures of multivariate uniform distributions with a particular Gamma distribution as a mixing distribution. The suggested algorithm is active in regularization under a variety of scenarios, as demonstrated by simulation examples. We have as well illustrated the advantages of the new method on prostate data example. Thus, both the simulation and the data of prostate cancer reveal great support for the employment of Bayesian group bridge CQR.

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