

Fuzzy Control Chart For Analysis Of N-Policy FM/FM/1vacation Queueing System With Server Start-Up And Time-Out

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Abstract:

This paper we constructs the N-policy FM/FM/1 vacation queueing system with server start-up and time-out by using fuzzy control chart based on Zedeh extension law to transform fuzzy queues into family of crisp queues. Arrival rate, service rate and vacation times will all be made by fuzzy nature. We derive the membership functions of the parameters of the control chart corresponding to the expected system length L and also confirmed the parameters of the control chart for fuzzy. We have also set an numerical example.

Keywords: Time out, N-Policy, Zedeh extension principle, fuzzy queues, controlchart.

1.Introduction

The principle of queues plays a significant part in our daily lives. Everyone must follow the queue in order to provide services to everybody to ensure prompt service for all. According to a given queue discipline, different types of servers serve different sorts of customers.

Vacation queueing system may be either single or multiple. In single vacation policy, immediately the system is free, the server takes exactly one vacation and provides service for the customers if exists any otherwise remains idle.

The term vacation queue was first began in 1970s. Doshi[1] wrote a good survey paper on vacation models.

Time out means taking a break at the time of working hours. Concept of time out was first introduced by Oliver C. Ibe[2] who derived explicit expressions for the average time for waiting on vacation queueing system with server time out.

K. Satish Kumar, K. Chandan et. al [3,4] have worked on this Timeout concepts of queues $M/M/1$, $M^x/G/1$ etc.derived expressions for the system length with N-policy, vacation, server startup and timeout.

Typically, in queuing theory, it is presupposed that the arrival time and the service time are distributed according to certain probabilities with fixed parameters. But in many real-world scenarios, labels like "fast," "slow," and "medium" may explain arrival patterns and service patterns more or less completely with probability distributions. By supposing the parameters of the system as fuzzy numbers, the queuing theory models thus developed have a extensive scope in real times. The fuzzy queues described by many researchers J.J. Buckley, Chen and many others [5,6,14] studied performance measures of various queueing systems with such fuzzy nature.

The control chart was originated in 1920s by Walter A. Shewhart of Bell Labs which gives a crisp idea of the state of a process by plotting the values of a variable under study on a chart bounded by upper and lower control limits. Montgomery [7] proposed a number of applications of Shewhart control charts in quality analysis in the manufacturing industries. T.poongodi and S. Muthulakshmi[13] constructed and studied the control chart for $M/M/S$ queueing model waiting time. A. Pandurangan & R. Varadharajan[8] analysed α -cut fuzzy control charts $\bar{\bar{X}} - \bar{\bar{R}}$ and $\bar{\bar{X}} - \bar{\bar{S}}$ based on trapezoidal fuzzy number. T.Poongodi, Dr.(Mrs)S.Muthulaksmi [9,10] analysed Fuzzy control chart for triangular fuzzy queueing model of $E_k/M/1$ and also derived control chart for fuzzy triangular number of mean waiting time in $M/M/S$ queueing model. Mohammed Shapique.A [11] developed the performance measures of fuzzy queueing system in waiting time for trapezoidal fuzzy numbers using fuzzy control charts.

We aimed to study on N-policy $FM/FM/1$ vacation queueing system with server startup and timeout using fuzzy control chart in this paper. Mysterious membership degrees built on Zadeh's [12] expansion law and we also given numerical examples.

2.Model Description

To apply Fuzzy condition, we have taken the expression of expected system length of N-policy FM/FM/1 vacation queueing system with server start-up and timeout taken from reference no [3]:

$$E(L) = \frac{\lambda^2}{\mu(\mu-\lambda)} + \frac{\lambda}{\mu} + \frac{c\lambda(\gamma N^2 + N\gamma + 2\lambda)}{2\mu\gamma(\gamma Nc + \lambda c + \gamma\lambda)}$$

The variance of system length is derived as

$$Var(L) = \frac{\lambda^2}{\mu(\mu-\lambda)} + \frac{\lambda}{\mu} \left[\frac{N(N-1)}{2} + \frac{\lambda}{\gamma} \left(\frac{\lambda}{\gamma} + N \right) \right] \frac{c\lambda(\gamma N^2 + N\gamma + 2\lambda)}{2\mu\gamma(\gamma Nc + \lambda c + \gamma\lambda)} - (E(L))^2$$

And optimal strategy

$$N^* = \sqrt{\frac{\left(\frac{2\lambda\mu\gamma + 2\lambda\mu c + c\lambda\gamma}{2c\mu\gamma}\right)^2 - \frac{2\lambda^2\mu - 2\lambda\gamma\mu + 2\lambda^2\gamma - \lambda\mu c + c^2\lambda}{c\mu\gamma}}{2(\mu-\lambda)\left\{c_b\frac{\lambda}{\mu} + c_v\left(\frac{\lambda}{c} + \frac{\lambda}{\gamma}\right) + c_m\frac{\lambda}{\gamma} + c_t\frac{\lambda}{c} + c_s\lambda\right\}} + \frac{\mu c_h}{2\lambda\mu\gamma + 2\lambda\mu c + c\lambda\gamma}} - \frac{2\lambda\mu\gamma}{2c\mu\gamma}$$

The upper and lower boundaries (control limits) for the expected system length are given by

$$UCL = E(L) + 3\sqrt{var(L)}$$

$$CL = E(L)$$

$$LCL = E(L) - 3\sqrt{var(L)}$$

3.Model with fuzzy parameter

We considered a single server queueing system which the customer arrives at a fuzzy arrival rate $\tilde{\lambda}$, fuzzy service rate $\tilde{\mu}$ and vacation time $\tilde{\gamma}$, \tilde{N} are approximately known. We construct the membership functions of the fuzzy control chart for expected system length of FM/FM/1 queueing system with server start-up and time-out and are given as follows

$$\tilde{\lambda} = \{(x, \eta_{\tilde{\lambda}}(x)) / x \in X\}$$

$$\tilde{\mu} = \{(y, \eta_{\tilde{\mu}}(y)) / y \in Y\}$$

$$\tilde{\gamma} = \{(z, \eta_{\tilde{\gamma}}(z)) / z \in Z\}$$

$$\tilde{N} = \{(z_1, \eta_{\tilde{N}}(z_1)) / z_1 \in Z_1\}$$

$\eta_{\tilde{\lambda}}(x), \eta_{\tilde{\mu}}(y)$ and $\eta_{\tilde{\gamma}}(z), \eta_{\tilde{N}}(z_1)$ are membership functions of triangular and trapezoidal fuzzy numbers. X, Y and Z, Z₁ are the help of the fuzzy number $\tilde{\lambda}, \tilde{\mu}$ and $\tilde{\gamma}, \tilde{N}$ respectively.

Let $P(x,y,z,z_1)$ and $\tilde{P}(\tilde{\lambda}, \tilde{\mu}, \tilde{\gamma}, \tilde{N})$ represent the control chart parameter in crisp and fuzzy environment of expected system length L respectively. Where P refers to the control standards of CL, UCL and LCL. If $\tilde{\lambda}, \tilde{\mu}$ and $\tilde{\gamma}, \tilde{N}$ are fuzzy parameters, then $\tilde{P}(\tilde{\lambda}, \tilde{\mu}, \tilde{\gamma}, \tilde{N})$ is also fuzzy. By applying Zadeh's extension law the control chart membership functions for the expected system length $\tilde{P}(\tilde{\lambda}, \tilde{\mu}, \tilde{\gamma}, \tilde{N})$ is defined as

$$\eta_{\tilde{P}(\tilde{\lambda}, \tilde{\mu}, \tilde{\gamma}, \tilde{N})}(\omega) = \sup_{x \in X, y \in Y, z \in Z, z_1 \in Z_1} \min\{\eta_{\tilde{\lambda}}(x), \eta_{\tilde{\mu}}(y), \eta_{\tilde{\gamma}}(z), \eta_{\tilde{N}}(z_1)\} \quad (1)$$

4. Control chart parameters for the expected system length of the customers

The fuzzy control limits for expected system length L is given by

$$CL(x,y,z)^L = \frac{\lambda^2}{\mu(\mu-\lambda)} + \frac{\lambda}{\mu} + \frac{c\lambda(\gamma N^2 + N\gamma + 2\lambda)}{2\mu\gamma(\gamma Nc + \lambda c + \gamma\lambda)}$$

$$Var(x,y,z)^L = \frac{\lambda^2}{\mu(\mu-\lambda)} + \frac{\lambda}{\mu} + \left[\frac{N(N-1)}{2} + \frac{\lambda}{\gamma} \left(\frac{\lambda}{\gamma} + N \right) \right] \frac{c\lambda(\gamma N^2 + N\gamma + 2\lambda)}{2\mu\gamma(\gamma Nc + \lambda c + \gamma\lambda)} - (CL(x,y,z))^2$$

$$UCL(x,y,z)^L = CL(x,y,z) + 3\sqrt{var(x,y,z)}$$
 and

$$LCL(x,y,z)^L = CL(x,y,z) - 3\sqrt{var(x,y,z)}$$

A mathematical procedure is developed for LCL, UCL and CL to obtain the desired membership functions based on α -cuts.

4.1. The α -cuts approach depend on the extension law

The α -cuts of $\tilde{\lambda}, \tilde{\mu}$ and $\tilde{\gamma}, \tilde{N}$ are crisp intervals and is defined as

$$\lambda_\alpha = \{x \in X / \eta_{\tilde{\lambda}}(x) \geq \alpha\} \quad (2)$$

$$\mu_\alpha = \{y \in Y / \eta_{\tilde{\mu}}(y) \geq \alpha\} \quad (3)$$

$$\gamma_\alpha = \{z \in Z / \eta_{\tilde{\gamma}}(z) \geq \alpha\} \quad (4)$$

$$N_\alpha = \{z_1 \in Z_1 / \eta_{\tilde{N}}(z_1) \geq \alpha\} \quad (5)$$

These crisp sets can be Expressed in this way

$$\lambda_\alpha = [x_\alpha^L, x_\alpha^U] = [\min_{x \in X} \{x \in X / \eta_{\tilde{\lambda}}(x) \geq \alpha\}, \{\max_{x \in X} x \in X / \eta_{\tilde{\lambda}}(x) \geq \alpha\}] \quad (6)$$

$$\mu_\alpha = [y_\alpha^L, y_\alpha^U] = [\min_{y \in Y} \{y \in Y / \eta_{\tilde{\mu}}(y) \geq \alpha\}, \{\max_{y \in Y} y \in Y / \eta_{\tilde{\mu}}(Y) \geq \alpha\}] \quad (7)$$

$$\gamma_\alpha = [z_\alpha^L, z_\alpha^U] = [\min_{z \in Z} \{z \in Z / \eta_{\tilde{\gamma}}(z) \geq \alpha\}, \{\max_{z \in Z} z \in Z / \eta_{\tilde{\gamma}}(z) \geq \alpha\}] \quad (8)$$

$$N_\alpha = [z_{1\alpha}^L, z_{1\alpha}^U] = [\min_{z_1 \in Z_1} \{z_1 \in Z_1 / \eta_{\tilde{\gamma}}(z_1) \geq \alpha\}, \{\max_{z_1 \in Z_1} z_1 \in Z_1 / \eta_{\tilde{\gamma}}(z) \geq \alpha\}] \quad (9)$$

The above intervals provide information on the arrival rate, the service and vacation time rate with possibility α .

The bounds of above intervals in (6), (7) and (8),(9) are basis of α and can be obtained as

$$x_\alpha^L = \min \eta_{\tilde{\lambda}}^{-1}(\alpha), x_\alpha^U = \max \eta_{\tilde{\lambda}}^{-1}(\alpha),$$

$$y_\alpha^L = \min \eta_{\tilde{\mu}}^{-1}(\alpha), y_\alpha^U = \max \eta_{\tilde{\mu}}^{-1}(\alpha)$$

$$z_\alpha^L = \min \eta_{\tilde{\gamma}}^{-1}(\alpha), z_\alpha^U = \max \eta_{\tilde{\gamma}}^{-1}(\alpha)$$

$$z_{1\alpha}^L = \min \eta_{\tilde{N}}^{-1}(\alpha), N_\alpha^U = \max \eta_{\tilde{N}}^{-1}(\alpha)$$

Hence, the membership function can be built by using α -cuts.

4.2. Building of membership function

We consider the membership functions of the limitations of the control chart for expected system length L. In equation (1), $\eta_{\tilde{CL}}(\omega)$ is the minimum standard of $\eta_{\tilde{\lambda}}(x), \eta_{\tilde{\mu}}(y)$ and $\eta_{\tilde{\gamma}}(z), \eta_{\tilde{\gamma}}(z_1)$ to allocate with the help of the membership function, we require to hold such that $\omega = CL(x,y,z)$ and $\eta_{\tilde{CL}}(\omega) = \alpha$ at least one of the following four cases

$$\left. \begin{aligned} \text{(i)} & : \eta_{\tilde{\lambda}}(x) = \alpha, \eta_{\tilde{\mu}}(y) \geq \alpha, \eta_{\tilde{\gamma}}(z) \geq \alpha, \eta_{\tilde{\gamma}}(z_1) \geq \alpha \\ \text{(ii)} & : \eta_{\tilde{\lambda}}(x) \geq \alpha, \eta_{\tilde{\mu}}(y) = \alpha, \eta_{\tilde{\gamma}}(z) \geq \alpha, \eta_{\tilde{\gamma}}(z_1) \geq \alpha \\ \text{(iii)} & : \eta_{\tilde{\lambda}}(x) \geq \alpha, \eta_{\tilde{\mu}}(y) \geq \alpha, \eta_{\tilde{\gamma}}(z) = \alpha, \eta_{\tilde{\gamma}}(z_1) \geq \alpha \\ \text{(iv)} & : \eta_{\tilde{\lambda}}(x) \geq \alpha, \eta_{\tilde{\mu}}(y) \geq \alpha, \eta_{\tilde{\gamma}}(z) \geq \alpha, \eta_{\tilde{\gamma}}(z_1) = \alpha \end{aligned} \right\} \quad (8)$$

From the definition of λ_α , μ_α and γ_α , N_α in equations (2)-(4), $x \in \lambda_\alpha$, $y \in \mu_\alpha$ and $z \in \gamma_\alpha$ may be replaced by $x \in [x_\alpha^L, x_\alpha^U]$, $y \in [y_\alpha^L, y_\alpha^U]$ and $z \in [z_\alpha^L, z_\alpha^U]$, $[z_{1\alpha}^L, z_{1\alpha}^U]$ respectively. The non-linear parametric programs (NLPs) are formulated in the following to find the upper and lower bounds of the α -cut of $\eta_{\bar{C}L}(\omega)$ corresponding to all four cases mentioned in (8)

Case (1):

$$(CL)_\alpha^{L_1} = \min \frac{\lambda^2}{\mu(\mu-\lambda)} + \frac{\lambda}{\mu} + \left[\frac{N(N-1)}{2} + \frac{\lambda}{\gamma} \left(\frac{\lambda}{\gamma} + N \right) \right] \frac{c\lambda(\gamma N^2 + N\gamma + 2\lambda)}{2\mu\gamma(\gamma Nc + \lambda c + \gamma\lambda)}$$

Subject to $x_\alpha^L \leq X \leq x_\alpha^U$, $y \in \mu_\alpha$ and $z \in \gamma_\alpha$, $z_1 \in N_\alpha$

$$(CL)_\alpha^{U_1} = \max \frac{\lambda^2}{\mu(\mu-\lambda)} + \frac{\lambda}{\mu} + \left[\frac{N(N-1)}{2} + \frac{\lambda}{\gamma} \left(\frac{\lambda}{\gamma} + N \right) \right] \frac{c\lambda(\gamma N^2 + N\gamma + 2\lambda)}{2\mu\gamma(\gamma Nc + \lambda c + \gamma\lambda)}$$

Subject to $x_\alpha^L \leq X \leq x_\alpha^U$, $y \in \mu_\alpha$ and $z \in \gamma_\alpha$, $z_1 \in N_\alpha$

case (ii):

$$(CL)_\alpha^{L_2} = \min \frac{\lambda^2}{\mu(\mu-\lambda)} + \frac{\lambda}{\mu} + \left[\frac{N(N-1)}{2} + \frac{\lambda}{\gamma} \left(\frac{\lambda}{\gamma} + N \right) \right] \frac{c\lambda(\gamma N^2 + N\gamma + 2\lambda)}{2\mu\gamma(\gamma Nc + \lambda c + \gamma\lambda)}$$

Subject to $x \in \lambda_\alpha$, $y_\alpha^L \leq Y \leq y_\alpha^U$, $y \in \mu_\alpha$ and $z \in \gamma_\alpha$, $z_1 \in N_\alpha$

$$(CL)_\alpha^{U_2} = \max \frac{\lambda^2}{\mu(\mu-\lambda)} + \frac{\lambda}{\mu} + \left[\frac{N(N-1)}{2} + \frac{\lambda}{\gamma} \left(\frac{\lambda}{\gamma} + N \right) \right] \frac{c\lambda(\gamma N^2 + N\gamma + 2\lambda)}{2\mu\gamma(\gamma Nc + \lambda c + \gamma\lambda)}$$

Subject to $x \in \lambda_\alpha$, $y_\alpha^L \leq Y \leq y_\alpha^U$, and $z \in \gamma_\alpha$, $z_1 \in N_\alpha$

case (iii):

$$(CL)_\alpha^{L_3} = \min \frac{\lambda^2}{\mu(\mu-\lambda)} + \frac{\lambda}{\mu} + \left[\frac{N(N-1)}{2} + \frac{\lambda}{\gamma} \left(\frac{\lambda}{\gamma} + N \right) \right] \frac{c\lambda(\gamma N^2 + N\gamma + 2\lambda)}{2\mu\gamma(\gamma Nc + \lambda c + \gamma\lambda)}$$

Subject to $x \in \lambda_\alpha$, $y \in \mu_\alpha$ and $z_\alpha^L \leq z \leq z_\alpha^U$, $z_1 \in N_\alpha$

$$(CL)_\alpha^{U_3} = \max \frac{\lambda^2}{\mu(\mu-\lambda)} + \frac{\lambda}{\mu} + \left[\frac{N(N-1)}{2} + \frac{\lambda}{\gamma} \left(\frac{\lambda}{\gamma} + N \right) \right] \frac{c\lambda(\gamma N^2 + N\gamma + 2\lambda)}{2\mu\gamma(\gamma Nc + \lambda c + \gamma\lambda)}$$

Subject to $x \in \lambda_\alpha$, $y \in \mu_\alpha$ and $z_\alpha^L \leq Z \leq z_\alpha^U$, $z_1 \in N_\alpha$

Case (IV)

$$(CL)_{\alpha}^{L_3} = \min \frac{\lambda^2}{\mu(\mu-\lambda)} + \frac{\lambda}{\mu} + \left[\frac{N(N-1)}{2} + \frac{\lambda}{\gamma} \left(\frac{\lambda}{\gamma} + N \right) \right] \frac{c\lambda(\gamma N^2 + N\gamma + 2\lambda)}{2\mu\gamma(\gamma Nc + \lambda c + \gamma\lambda)}$$

Subject to $x \in \lambda_{\alpha}, y \in \mu_{\alpha}$ and $z \in \gamma_{\alpha}, z_{1\alpha}^L \leq z_1 \leq z_{1\alpha}^U$

$$(CL)_{\alpha}^{U_3} = \max \frac{\lambda^2}{\mu(\mu-\lambda)} + \frac{\lambda}{\mu} + \left[\frac{N(N-1)}{2} + \frac{\lambda}{\gamma} \left(\frac{\lambda}{\gamma} + N \right) \right] \frac{c\lambda(\gamma N^2 + N\gamma + 2\lambda)}{2\mu\gamma(\gamma Nc + \lambda c + \gamma\lambda)}$$

Subject to $x \in \lambda_{\alpha}, y \in \mu_{\alpha}$ and $z \in \gamma_{\alpha}, z_{1\alpha}^L \leq z_1 \leq z_{1\alpha}^U$

Using the above cases (1),(2) we find the left appear $L(\omega)$ and the right appear $R(\omega)$ of $\eta_{\widetilde{CL}}(\omega)$ and we used to notice the lower bound $(CL)_{\alpha}^L$ and the upper bound $(CL)_{\alpha}^U$ of α -cuts of \widetilde{CL} .

These may be rewritten as

$$(CL)_{\alpha}^L = \min_{x \in X, y \in Y, z \in Z, z_1 \in Z_1} \frac{\lambda^2}{\mu(\mu-\lambda)} + \frac{\lambda}{\mu} + \left[\frac{N(N-1)}{2} + \frac{\lambda}{\gamma} \left(\frac{\lambda}{\gamma} + N \right) \right] \frac{\mu}{\mu-\lambda} P_0^0$$

Subject to $x_{\alpha}^L \leq x \leq x_{\alpha}^U, y_{\alpha}^L \leq y \leq y_{\alpha}^U, z_{\alpha}^L \leq z \leq z_{\alpha}^U, z_{1\alpha}^L \leq z_1 \leq z_{1\alpha}^U$ (9)

$$(CL)_{\alpha}^U = \max_{x \in X, y \in Y, z \in Z} \frac{\lambda^2}{\mu(\mu-\lambda)} + \frac{\lambda}{\mu} + \left[\frac{N(N-1)}{2} + \frac{\lambda}{\gamma} \left(\frac{\lambda}{\gamma} + N \right) \right] \frac{\mu}{\mu-\lambda} P_0^0$$

Subject to $x_{\alpha}^L \leq x \leq x_{\alpha}^U, y_{\alpha}^L \leq y \leq y_{\alpha}^U, z_{\alpha}^L \leq z \leq z_{\alpha}^U, z_{1\alpha}^L \leq z_1 \leq z_{1\alpha}^U$ (10)

At least one x, y and z, z_1 must lie within the bound of equations (9), (10) to satisfy the condition $\eta_{\widetilde{CL}}(\omega) = \alpha$. This set of mathematical procedures falls into the list of non-linear parametric programs, which facilitate a planned process of how optimal solutions evolve for the ranges of $x_{\alpha}^L, x_{\alpha}^U, y_{\alpha}^L, y_{\alpha}^U, z_{\alpha}^L, z_{\alpha}^U, z_{1\alpha}^L, z_{1\alpha}^U$ and α having the interval $[0,1]$. The interval $[(CL)_{\alpha}^L, (CL)_{\alpha}^U]$ is a crisp interval constitute the α -cuts of (\widetilde{CL}) . A new based on the extension law and the convexity possessions of fuzzy numbers we obtained $[(CL)_{\alpha_1}^L, (CL)_{\alpha_1}^U] \subseteq [(CL)_{\alpha_2}^L, (CL)_{\alpha_2}^U]$ for $0 < \alpha_4 < \alpha_3 < \alpha_2 < \alpha_1 < 1$. On the other hand, as α increases, the value of $(CL)_{\alpha}^L$ increase and $(CL)_{\alpha}^U$ decrease. The α -cuts provide a feasible, range of performance measures. A range at $\alpha=0$ is calculated for the help of the performance measures and the all most all feasible range at $\alpha=1$ is computed for the performance measure. If both the lower and upper bounds $(CL)_{\alpha}^L, (CL)_{\alpha}^U$ of the α -cuts of (\widetilde{CL}) are revertible with respect to α , than a left function appearance $L(\omega)$ and a right function appearance $R(\omega)$ may be obtained as $L(\omega) = [(CL)_{\alpha}^L]^{-1}$ and

$R(\omega) = [(CL)_\alpha^U]^{-1}$. Then the membership function $\eta_{\widetilde{CL}}(\omega)$ can be expressed as

$$\eta_{\widetilde{CL}}(\omega) = \begin{cases} L(\omega), & (CL)_{\alpha=0}^L \leq \omega \leq (CL)_{\alpha=1}^L \\ 1, & (CL)_{\alpha=1}^L \leq \omega \leq (CL)_{\alpha=1}^U \\ R(\omega), & (CL)_{\alpha=1}^U \leq \omega \leq (CL)_{\alpha=0}^U \end{cases}$$

Yager index given the representative value of the fuzzy number and region recompense is used to defuzzify (\widetilde{CL}) of the expected system length into a crisp one. The Robust ranking index is

$$Y(\widetilde{CL}) = \frac{1}{2} \int_0^1 [(CL)_\alpha^L + (CL)_\alpha^U] d\alpha$$

The membership functions $\eta_{\widetilde{UCL}}(\omega)$ and $\eta_{\widetilde{LCL}}(\omega)$ and Yager indices can be obtained by following the same procedure for the control chart parameters namely UCL and LCL.

4.3 Control chart parameters for expected system length

The standards of the fuzzy control chart for expected length is

$$CL(x,y,z) = \frac{\lambda^2}{\mu(\mu-\lambda)} + \frac{\lambda}{\mu} + \frac{c\lambda(\gamma N^2 + N\gamma + 2\lambda)}{2\mu\gamma(\gamma Nc + \lambda c + \gamma\lambda)}$$

$$UCL(x,y,z) = CL(x,y,z) + 3\sqrt{var(x,y,z)}$$

$$LCL(x,y,z) = CL(x,y,z) - 3\sqrt{var(x,y,z)}$$

By following the same method as we used in the previous section, we construct the membership functions and the Yager ranking indices of the parameters of fuzzy control chart relating to the expected system length L.

5. Numerical analysis

5.1. Triangular fuzzy number

Consider an FM/FM/1, Queueing System with Server startup and time out where arrival stream and service stream and idle time are triangular fuzzy numbers denoted by $\lambda = [1,2,3]$; $\mu = [5,6,7]$; $\gamma = [2,3,4]$, $C=1, C_b=300, C_m=200, C_t=30, C_s=500, C_v=15$ and $C_h=5$. The upper bound and lower bound of $\tilde{\lambda}$, $\tilde{\mu}$ and $\tilde{\gamma}$ are obtained as

$$[x_{\alpha}^L, x_{\alpha}^U] = [1+\alpha, 3-\alpha], [y_{\alpha}^L, y_{\alpha}^U] = [5+\alpha, 7-\alpha], [z_{\alpha}^L, z_{\alpha}^U] = [2+\alpha, 4-\alpha]$$

1. Optimal N-policy(N*)

$$N^* = \sqrt{\left(\frac{\left(\frac{2\alpha^3+19\alpha^2+49\alpha+32}{2\alpha^2+14\alpha+20} \right)^2 - \frac{6\alpha^3+38\alpha^2+65\alpha+29}{\alpha^2+7\alpha+10}}{8 \frac{545\alpha^3+4875\alpha^2+11455\alpha+7125}{\alpha^2+7\alpha+10}} \right) / (25 + 2\alpha) - \frac{2\lambda\mu\gamma + 2\lambda\mu c + c\lambda\gamma}{2c\mu\gamma}}$$

Control chart parameter for expected system length L as follows

$$CL(x, y, z)_{\alpha}^L = \frac{\alpha^3+11\alpha^2+35\alpha+25}{4\alpha^2+40\alpha+100} + \frac{\alpha^2 N^2 + N\alpha^2 + 2\alpha^2 + 2N^2 + 3\alpha N^2 + 2N + 3N\alpha + 3\alpha + 2}{2(\alpha^2 + 7\alpha + 10)(\alpha^2 + N\alpha + 4\alpha + 2N + 3)}$$

$$CL(x, y, z)_{\alpha}^U = \frac{3\alpha^2-16\alpha+21}{2\alpha^2-18\alpha+28} + \frac{\alpha^2 N^2 + N\alpha^2 + 2\alpha^2 + \alpha^2 N - 12\alpha + 12N^2 - 7\alpha N^2 + 12N - 7N\alpha + 18}{2(\alpha^2 - 11\alpha + 28)(\alpha^2 - N\alpha - 8\alpha + 4N + 15)}$$

$$var(x, y, z)_{\alpha}^L = \frac{\alpha^3+11\alpha^2+35\alpha+25}{4\alpha^2+40\alpha+100} + \left[\frac{N(N-1)}{2} + \frac{\alpha^2 + \alpha^2 N + 3N\alpha + 2N + 2\alpha + 1}{\alpha^2 + 4\alpha + 4} \right] \frac{\alpha^2 N^2 + N\alpha^2 + 2\alpha^2 + 2N^2 + 3\alpha N^2 + 2N + 3N\alpha + 3\alpha + 2}{2(\alpha^2 + 7\alpha + 10)(\alpha^2 + N\alpha + 4\alpha + 2N + 3)} - (CL(x, y, z))^2$$

$$var(x, y, z)_{\alpha}^U = \frac{3\alpha^2-16\alpha+21}{2\alpha^2-18\alpha+28} + \left[\frac{N(N-1)}{2} + \frac{\alpha^2 + \alpha^2 N - 7N\alpha + 12N - 5\alpha + 6}{\alpha^2 - 8\alpha + 16} \right] \frac{\alpha^2 N^2 + N\alpha^2 + 2\alpha^2 + \alpha^2 N - 12\alpha + 12N^2 - 7\alpha N^2 + 12N - 7N\alpha + 18}{2(\alpha^2 - 11\alpha + 28)(\alpha^2 - N\alpha - 8\alpha + 4N + 15)} - (CL(x, y, z))^2$$

$$UCL(x, y, z)_{\alpha}^L = CL(x, y, z)_{\alpha}^L + 3\sqrt{var(x, y, z)_{\alpha}^L}$$

$$LCL(x, y, z)_{\alpha}^L = CL(x, y, z)_{\alpha}^L - 3\sqrt{var(x, y, z)_{\alpha}^L}$$

$$UCL(x, y, z)_{\alpha}^U = CL(x, y, z)_{\alpha}^U + 3\sqrt{var(x, y, z)_{\alpha}^U}$$

$$LCL(x, y, z)_{\alpha}^U = CL(x, y, z)_{\alpha}^U - 3\sqrt{var(x, y, z)_{\alpha}^U}$$

The values control chart parameters For different values of $\alpha \in [0,1]$ are calculated in table.1

α	x_{α}^L	x_{α}^U	y_{α}^L	y_{α}^U	z_{α}^L	z_{α}^U	N_{α}^L	N_{α}^U	CL_{α}^L
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0	1	3	5	7	2	4	13.48840615	17.80681594	0.905258153
0.1	1.1	2.9	5.1	6.9	2.1	3.9	13.96098923	17.73442948	0.966563039
0.2	1.2	2.8	5.2	6.8	2.2	3.8	14.39892226	17.65505171	1.023615857
0.3	1.3	2.7	5.3	6.7	2.3	3.7	14.80666822	17.568138	1.076847711
0.4	1.4	2.6	5.4	6.6	2.4	3.6	15.18782304	17.47308481	1.126647776
0.5	1.5	2.5	5.5	6.5	2.5	3.5	15.54533299	17.369221	1.173365244
0.6	1.6	2.4	5.6	6.4	2.6	3.4	15.88164699	17.25579753	1.217312402
0.7	1.7	2.3	5.7	6.3	2.7	3.3	16.19882626	17.13197493	1.258768092
0.8	1.8	2.2	5.8	6.2	2.8	3.2	16.49862488	16.99680836	1.297981178
0.9	1.9	2.1	5.9	6.1	2.9	3.1	16.78255011	16.84922919	1.33517383
1.0	2	2	6	6	3	3	17.05190842	16.68802249	1.370544523

CL_{α}^U	var_{α}^L	var_{α}^U	UCL_{α}^L	UCL_{α}^U	LCL_{α}^L	LCL_{α}^U
1.585970704	59.20220636	134.8056016	23.98814916	36.41771505	- 22.1776328 5	- 33.24577364
1.584935172	67.15638953	134.8874483	25.55126368	36.42725189	- 23.6181376 1	- 33.25738155
1.583600273	74.95436767	134.8004747	26.99647302	36.41468226	-24.9492413	- 33.24748172
1.581966185	82.5481933	134.5301199	28.3336586	36.37810217	- 26.1799631 8	-33.2141698
1.580042113	89.9025656	134.0609485	29.57173681	36.31544965	- 27.3184412 6	- 33.15536542
1.577850461	96.99213659	133.3766453	30.71874101	36.22449255	- 28.3720105 2	- 33.06879163
1.575432948	103.799398	132.4600278	31.78190927	36.10281701	- 29.3472844 6	- 32.95195111
1.572860202	110.3130184	131.293151	32.76776944	35.94782725	- 30.2502332 5	- 32.80210684
1.570250788	116.5265307	129.8581175	33.68221771	35.75684257	- 31.0862553 6	-32.616341
1.56782899	122.4372912	128.1422441	34.53058949	35.52780834	- 31.8602418 3	- 32.39215036

1.566150499	128.0456531	126.1641612	35.31772228	35.2629968	- 32.5766332 3	- 32.13069581
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From above tables at $\alpha = 0$ we observe that the value of CL lie in the range $[0.9052, 1.5859]$ which implies that CL of E(L) can't exceed 1.5859 or fall before 0.9052 and UCL lies in the range $23.9881 \leq UCL \leq 36.4177$.

From above tables at $\alpha = 1$ we observe that the value of CL lie in the range $[1.3705, 1.5661]$ which implies that CL of E(L) can't exceed 1.5661 or fall before 1.3705 and UCL lies in the range $35.3177 \leq UCL \leq 35.2629$.

The expected CL and UCL of E(L) are obtained by applying the Yager ranking index

$$R(\widetilde{CL}) = \frac{1}{2} \int_0^1 [(CL)_\alpha^L + (CL)_\alpha^U] d\alpha = 1.24$$

$$R(\widetilde{UCL}) = \frac{1}{2} \int_0^1 [(UCL)_\alpha^L + (LCL)_\alpha^U] d\alpha = 30.20$$

By using MATLAB the inverse function of L(z) and R(z) of $(CL)_\alpha^L, (CL)_\alpha^U, (UCL)_\alpha^L$ & $(UCL)_\alpha^U$ are obtain the membership function of

$\eta_{\widetilde{CL}}(\omega)$ and $\eta_{\widetilde{UCL}}(\omega)$ can stated as

$$\eta_{\widetilde{CL}}(\omega) = \begin{cases} L(z), & 0.9052 \leq \omega \leq 1.3705 \\ 1, & 1.3705 \leq \omega \leq 1.5661 \\ R(z), & 1.5661 \leq \omega \leq 1.5859 \end{cases}$$

$$\eta_{\widetilde{UCL}}(\omega) = \begin{cases} L(z), & 23.9881 \leq \omega \leq 35.3177 \\ 1, & 35.2629 \leq \omega \leq 35.3177 \\ R(z), & 35.2629 \leq \omega \leq 36.4177 \end{cases}$$

Figure :1.1 (Triangular CL(L))

Values of α

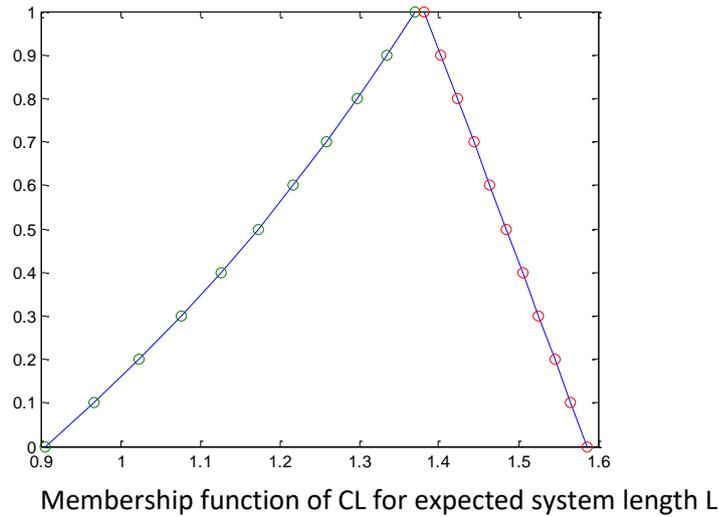
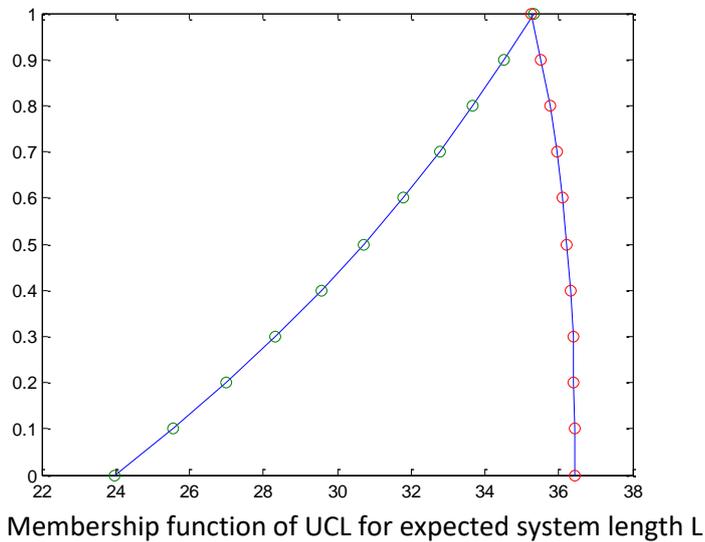


Figure:1.2 (Triangular UCL (L))

Values of α



The graph of the membership function of $\eta_{\overline{CL}}(\omega)$, $\eta_{\overline{UCL}}(\omega)$ corresponding to α -cuts relating to $E(L)$ are shown in fig.1.1 and 1.2 respectively. And also given the graphs of the optimum threshold N^* and variance (L).

Figure :1.3 (Triangular N)

Values of α

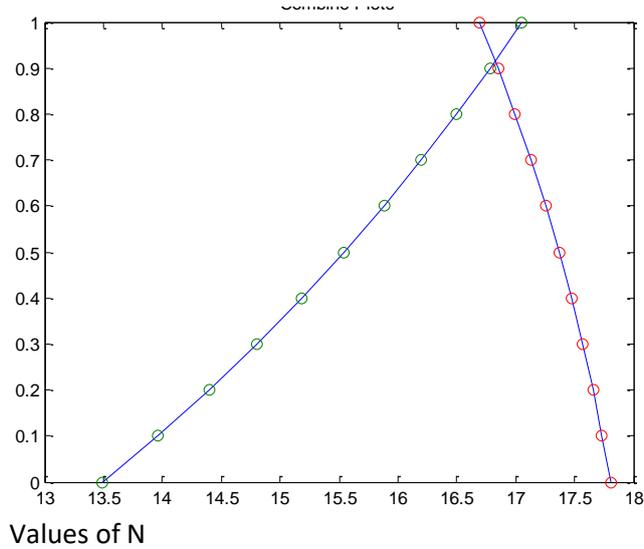
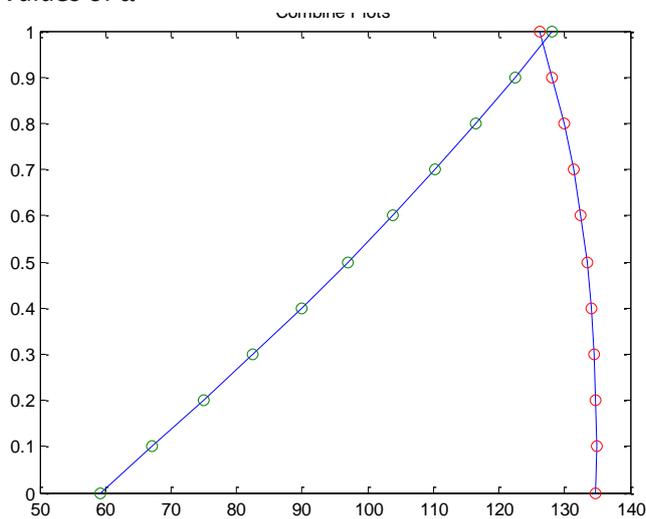


Figure:1.4(Triangular (var L))

Values of α



Values of var (L)

5.2.Trapezoidal fuzzy numbers

Consider an FM/FM/1, Queueing System with Server startup and time out where arrival pattern and service pattern are triangular fuzzy numbers denoted by $\lambda=[1,2,3,4]$; $\mu = [5,6,7,8]$; $\gamma = [2,3,4,5]$, $C=1$, $C_b=300$,

$C_m=200, C_t=30, C_s=500, C_v=15$ and $C_h=5$. The upper bound and lower bound of $\tilde{\lambda}, \tilde{\mu}$ and $\tilde{\gamma}$ are obtained as

$$[x_\alpha^L, x_\alpha^U] = [1+\alpha, 4-\alpha], [y_\alpha^L, y_\alpha^U] = [5+\alpha, 8-\alpha], [z_\alpha^L, z_\alpha^U] = [2+\alpha, 5-\alpha]$$

α	x_α^L	x_α^U	y_α^L	y_α^U	z_α^L	z_α^U	N_α^L	N_α^U	CL_α^L
0	1	3	5	7	2	4	13.48840615	20.79204693	0.905258153
0.1	1.1	2.9	5.1	6.9	2.1	3.9	13.96098923	20.62494041	0.966563039
0.2	1.2	2.8	5.2	6.8	2.2	3.8	14.39892226	20.45101911	1.023615857
0.3	1.3	2.7	5.3	6.7	2.3	3.7	14.80666822	20.269769	1.076847711
0.4	1.4	2.6	5.4	6.6	2.4	3.6	15.18782304	20.08062312	1.126647776
0.5	1.5	2.5	5.5	6.5	2.5	3.5	15.54533299	19.88295408	1.173365244
0.6	1.6	2.4	5.6	6.4	2.6	3.4	15.88164699	19.67606533	1.217312402
0.7	1.7	2.3	5.7	6.3	2.7	3.3	16.19882626	19.45918072	1.258768092
0.8	1.8	2.2	5.8	6.2	2.8	3.2	16.49862488	19.23143198	1.297981178
0.9	1.9	2.1	5.9	6.1	2.9	3.1	16.78255011	18.99184359	1.33517383
1.0	2	2	6	6	3	3	17.05190842	18.73931437	1.370544523

CL_α^U	var_α^L	var_α^U	UCL_α^L	UCL_α^U	LCL_α^L	LCL_α^U
1.888364389	59.20220636	218.1629487	23.9881491 6	46.1993849	- 22.1776328 5	-42.42265612
1.865487616	67.15638953	214.8591988	25.5512636 8	45.8397163	- 23.6181376 1	-42.10874107
1.842204418	74.95436767	211.4314328	26.9964730 2	45.4642504	-24.9492413	-41.77984156
1.818469582	82.5481933	207.8721809	28.3336586	45.07178885	- 26.1799631 8	-41.43484969
1.794233105	89.9025656	204.1733682	29.5717368 1	44.66100712	- 27.3184412 6	-41.07254091
1.769439611	96.99213659	200.326257	30.7187410 1	44.23043716	- 28.3720105 2	-40.69155794
1.744027681	103.799398	196.3213797	31.7819092 7	43.77844711	- 29.3472844 6	-40.29039175

1.71792908	110.3130184	192.1484643	32.7677694 4	43.30321709	- 30.2502332 5	-39.86735893
1.691067859	116.5265307	187.7963486	33.6822177 1	42.80271022	- 31.0862553 6	-39.4205745
1.663359317	122.4372912	183.252882	34.5305894 9	42.27463778	- 31.8602418 3	-38.94791914
1.634708776	128.0456531	178.5048135	35.3177222 8	41.71641684	- 32.5766332 3	-38.44699928

From above tables at $\alpha = 0$ we observe that the value of CL lie in the range $[0.9052, 1.8883]$ which implies that CL of E(L) can't exceed 1.8883 or fall before 0.9052 and UCL lies in the range $23.9881 \leq UCL \leq 46.1993$. From above tables at $\alpha = 1$ we observe that the value of CL lie in the range $[1.3705, 1.6347]$ which implies that CL of E(L) can't exceed 1.6347 or fall before 1.3705 and UCL lies in the range $35.3177 \leq UCL \leq 41.7164$

By applying Robust ranking technique the expected CL and UCL of E(L) are

$$Y(\widetilde{CL}) = \frac{1}{2} \int_0^1 [(CL)_\alpha^L + (CL)_\alpha^U] d\alpha = 1.39$$

$$Y(U\widetilde{CL}) = \frac{1}{2} \int_0^1 [(UCL)_\alpha^L + (LCL)_\alpha^U] d\alpha = 1.50$$

By using MATLAB the inverse function of L(z) and R(z) of $(CL)_\alpha^L$, $(CL)_\alpha^U$, $(UCL)_\alpha^L$ & $(UCL)_\alpha^U$ are obtain the membership function of

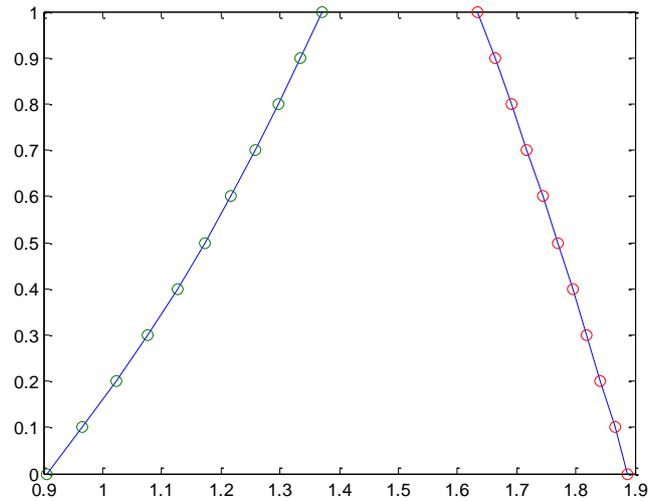
$\eta_{\widetilde{CL}}(\omega)$ and $\eta_{U\widetilde{CL}}(\omega)$ can stated as

$$\eta_{\widetilde{CL}}(\omega) = \begin{cases} L(z), & 0.9052 \leq \omega \leq 1.3705 \\ 1, & 1.3705 \leq \omega \leq 1.6347 \\ R(z), & 1.6347 \leq \omega \leq 1.888 \end{cases}$$

$$\eta_{U\widetilde{CL}}(\omega) = \begin{cases} L(z), & 23.9881 \leq \omega \leq 35.3177 \\ 1, & 35.3177 \leq \omega \leq 41.7164 \\ R(z), & 41.7164 \leq \omega \leq 46.1993 \end{cases}$$

Figure 2.1 (Trapezoidal CL (L))

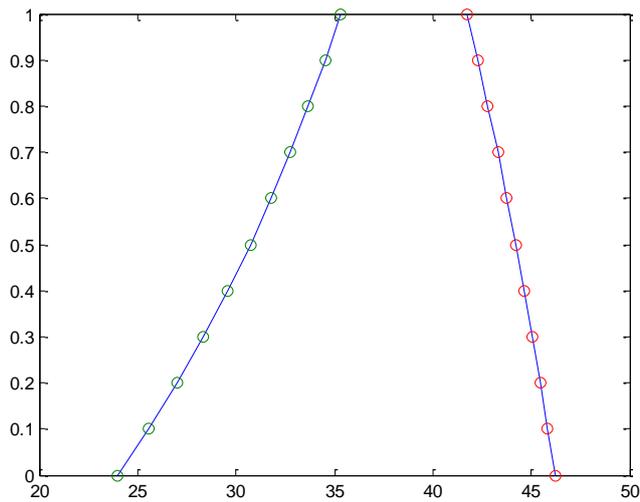
Values of α



Membership function of CL for expected system length L

Figure 2.2 Trapezoidal UCL(L)

Values of α



Membership function of UCL for expected system length L

The graph of the membership function of $\eta_{\overline{CL}}(\omega)$, $\eta_{\overline{UCL}}(\omega)$ corresponding to α -cuts relating to $E(L)$ are shown in fig.2.1 and 2.2 respectively. And also given the graphs of the optimum threshold N^* and variance (L).

Figure 2.3 Trapezoidal(N)

Values of α

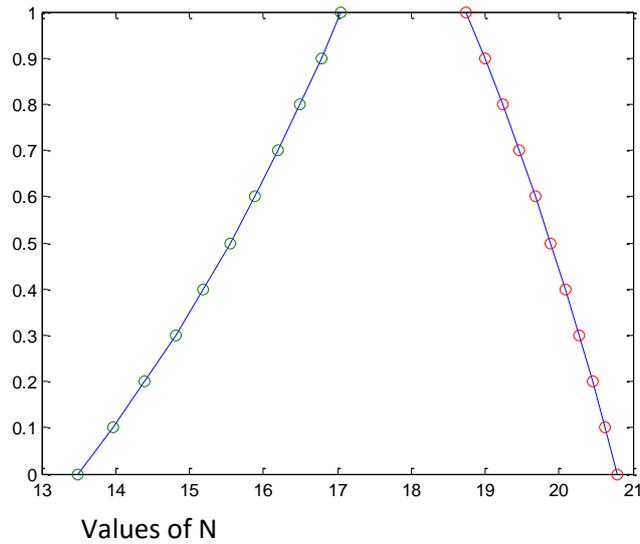
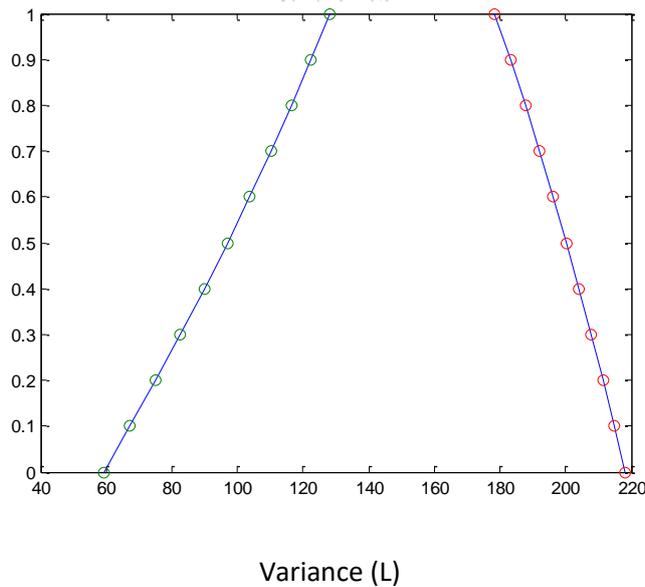


Figure 2.4 (Trapezoidal var(L))

Values of α



Conclusion

In this paper, we constructed the expected system length (L) for an N-policy FM/FM/1 vacation queueing system with server start-up and time-out using fuzzy control chart and also constructed the membership function of triangular and trapezoidal fuzzy numbers.

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